# PIMars 6-Axis Nanopositioning Stage

#### High-Precision Nanopositioner with 6 Degrees of Freedom



### P-562.6CD

- 6 motion axes: 3 × linear, 3 × rotational
- Travel ranges to 200 μm linear and to 1 mrad tip/tilt angle
- Parallel kinematics for faster response times and higher multi-axis accuracy
- Highest linearity due to capacitive sensors
- Zero-play, high-precision flexure guide system
- Excellent scanning flatness
- Clear aperture 66 mm × 66 mm
- Outstanding lifetime due to PICMA<sup>®</sup> piezo actuators
- UHV-compatible to 10<sup>-9</sup> hPa

#### **Application fields**

- Scanning microscopy
- Super-resolution microscopy
- Biotechnology
- Mask/wafer positioning
- Sample positioning
- Interferometry
- Metrology

#### Outstanding lifetime thanks to PICMA° piezo actuators

The PICMA<sup>\*</sup> piezo actuators are all-ceramic insulated. This protects them against humidity and failure resulting from an increase in leakage current. PICMA<sup>\*</sup> actuators offer an up to ten times longer lifetime than conventional polymer-insulated actuators. 100 billion cycles without a single failure are proven.

#### Subnanometer resolution with capacitive sensors

Capacitive sensors measure with subnanometer resolution without contacting. They guarantee excellent linearity of motion, long-term stability, and a bandwidth in the kHz range.

#### High guiding accuracy due to zero-play flexure guides

Flexure guides are free of maintenance, friction, and wear, and do not require lubrication. Their stiffness allows high load capacity and they are insensitive to shock and vibration. They work in a wide temperature range.

#### Automatic configuration and fast component exchange

Mechanics and controllers can be combined as required and exchanged quickly. All servo and linearization parameters are stored in the ID chip of the D-sub connector of the mechanics. The autocalibration function of the digital controllers uses this data each time the controller is switched on.

#### High tracking accuracy in the nanometer range due to parallel position measuring

All degrees of freedom are measured against a single fixed reference. Undesired crosstalk between axes can be actively compensated (active guiding) in real time (depending on the bandwidth). High tracking accuracy is achieved in the nanometer range even in dynamic operation.

#### Suitable for sophisticated vacuum applications

All components used in the piezo systems are excellently suited for use in vacuum. No lubricant or grease is necessary for operating. Polymer-free piezo systems allow particularly low outgas rates.



| Motion                       | Unit | Toleran-<br>ce | P-562.6CD          |
|------------------------------|------|----------------|--------------------|
| Active axes                  |      |                | Χ, Υ,Ζ, θΧ, θΥ, θΖ |
| Travel range in X            | μm   |                | 200                |
| Travel range in Y            | μm   |                | 200                |
| Travel range in Z            | μm   |                | 200                |
| Rotation range in $\theta X$ | mrad |                | ±0.5               |
| Rotation range in $\theta$ Y | mrad |                | ±0.5               |
| Rotation range in $\theta Z$ | mrad |                | ±0.5               |
| Linearity error in X         | %    | Тур.           | 0.01               |
| Linearity error in Y         | %    | Тур.           | 0.01               |
| Linearity error in Z         | %    | Тур.           | 0.01               |
| Linearity error in θX        | %    | Тур.           | 0.1                |
| Linearity error in θY        | %    | Тур.           | 0.1                |
| Linearity error in θZ        | %    | Тур.           | 0.1                |
| Flatness                     | nm   | Тур.           | <15                |

| Positioning                             | Unit | Toleran-<br>ce | P-562.6CD                               |
|---|------|----------------|---|
| Unidirectional repeatabili-<br>ty in X  | nm   | Тур.           | ±2                                      |
| Unidirectional repeatabili-<br>ty in Y  | nm   | Тур.           | ±2                                      |
| Unidirectional repeatabili-<br>ty in Z  | nm   | Тур.           | ±3                                      |
| Unidirectional repeatabili-<br>ty in θX | μrad | Тур.           | ±0.1                                    |
| Unidirectional repeatabili-<br>ty in θΥ | µrad | Тур.           | ±0.1                                    |
| Unidirectional repeatabili-<br>ty in θΖ | μrad | Тур.           | ±0.15                                   |
| Integrated sensor                       |      |                | Capacitive, indirect position measuring |
| System resolution in X                  | nm   | Тур.           | 1                                       |
| System resolution in Y                  | nm   | Тур.           | 1                                       |
| System resolution in Z                  | nm   | Тур.           | 1                                       |
| System resolution in θX                 | μrad | Тур.           | 0.1                                     |
| System resolution in $\theta Y$         | μrad | Тур.           | 0.1                                     |
| System resolution in $\theta Z$         | μrad | Тур.           | 0.1                                     |

| Drive Properties            | Unit | Toleran-<br>ce | P-562.6CD             |
|-----------------------------|------|----------------|-----------------------|
| Drive type                  |      |                | Piezo actuator/PICMA® |
| Electrical capacitance in X | μF   | ±20%           | 7.4                   |
| Electrical capacitance in Y | μF   | ±20%           | 7.4                   |
| Electrical capacitance in Z | μF   | ±20%           | 14.8                  |



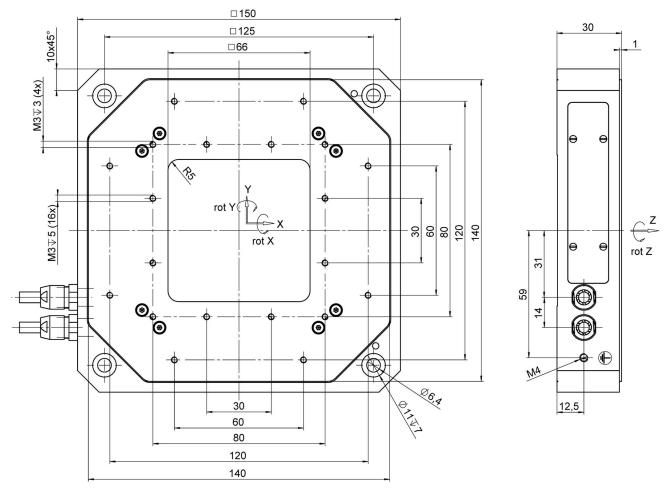
| Mechanical Properties             | Unit | Toleran-<br>ce | P-562.6CD  |
|-----------------------------------|------|----------------|--|
| Resonant frequency in X, unloaded | Hz   | ±20%           | 110  |
| Resonant frequency in Y, unloaded | Hz   | ±20%           | 110  |
| Resonant frequency in Z, unloaded | Hz   | ±20%           | 190  |
| Permissible push force in<br>X    | N    | Max.           | 50   |
| Permissible push force in<br>Y    | N    | Max.           | 50   |
| Permissible push force in<br>Z    | N    | Max.           | 60   |
| Permissible pull force in X       | N    | Max.           | 40   |
| Permissible pull force in Y       | N    | Max.           | 40   |
| Permissible pull force in Z       | N    | Max.           | 60   |
| Guide                             |      |                | Flexure guide/Flexure guide with lever amplification |
| Overall mass                      | g    | ±5%            | 1450   |
| Material                          |      |                | Aluminum   |

| Miscellaneous                        | Unit | Toleran-<br>ce | P-562.6CD          |
|--------------------------------------|------|----------------|--------------------|
| Operating temperature range          | °C   |                | -20 to 80          |
| Vacuum class                         | hPa  |                | 10 <sup>-9</sup>   |
| Connector                            |      |                | 2 × D-sub 25W3 (m) |
| Cable length                         | m    | ±10 mm         | 1.5                |
| Recommended controllers<br>/ drivers |      |                | E-712              |

The resolution of the system is limited only by the noise of the amplifier and the measuring technology because PI piezo nanopositioning systems are free of friction. Other travel ranges on request.



## Drawings / Images



P-562.6CD, dimensions in mm. Note that a comma is used in the drawings instead of a decimal point.

## Order Information

#### P-562.6CD

PIMars 6-axis nanopositioning stage; 200  $\mu$ m × 200  $\mu$ m × 200  $\mu$ m travel range (X × Y × Z); 1 mrad × 1 mrad × 1 mrad rotational angle ( $\theta$ X ×  $\theta$ Y ×  $\theta$ Z); capacitive, indirect position measuring; vacuum compatible to 10<sup>-9</sup> hPa; 2 × D-sub 25W3 (m) connector; 1. 5 m cable length